

**AMENDMENTS TO THE CLAIMS**

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Claim 1. (Canceled).

2. (Currently Amended) A manipulator according to claim [1]11, wherein the supporting arm comprises an angled part which permits the cabling to be held stretched centrally over the first arm.

3. (Currently Amended) A manipulator according to claim [1]11, wherein the auxiliary arm is arranged at a turning disc of the manipulator.

Dr 4. (Currently Amended) A manipulator according to claim [1]11, wherein the supporting arm and the auxiliary arm support a bendable tube[, in which] for reception of the cabling [is running].

5. (Currently Amended) A manipulator according to claim [1]11, wherein ~~a spiral spring is arranged around the third axis for influencing the supporting arm~~ has a spiral spring for exerting a spring force on the cabling.

6. (Previously Amended) A manipulator according to claim 5, wherein the spiral spring is housed in a container.

Claims 7-9 (Canceled)

10. (Canceled)

11. (New) An anthropomorphic manipulator, comprising an upper arm which comprises a rear arm part and which further comprises a front arm part having a longitudinal axis, the front arm part being arranged for rotation about said longitudinal

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axis, cabling extending along the said arm parts and being arranged as to be wound around said front arm part when said front arm part is rotated about said longitudinal axis, the front arm part being journalled in bearings in the rear arm part for relative rotation, a supporting device for guiding and holding the cabling in a stretched condition at the front arm part, the supporting device comprising a supporting arm rotatably arranged on the rear arm part and an auxiliary arm arranged at the front arm part.

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